5G for cooperative & connected automated MOBIility on X-border corridors

5GTNF Results and Demo Seminar

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Background and motivation of 5G-MOBIX

Higher Levels of Vehicle Automation with 5G

ADAS+ - Partial automation
Driver supervises the ADS

Conditinal automation

Driver "out of the loop" but need to take control on request by the ADS

High/Full automation

Driver out of the loop & no need to take control – can be driverless

SAE automation levels

L2

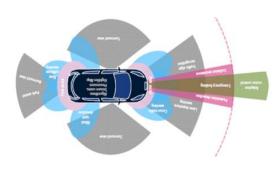


L3



L4/L5

In-vehicle sensors and ADS



Higher environment perception using connected sensors and computing outside the vehicle









fusion





4G/5G Communications positioning

Multimode C-V2X Direct



Precise











Computer

vision

ADS: Automated Driving System

SAE: Society of Automotive Engineers

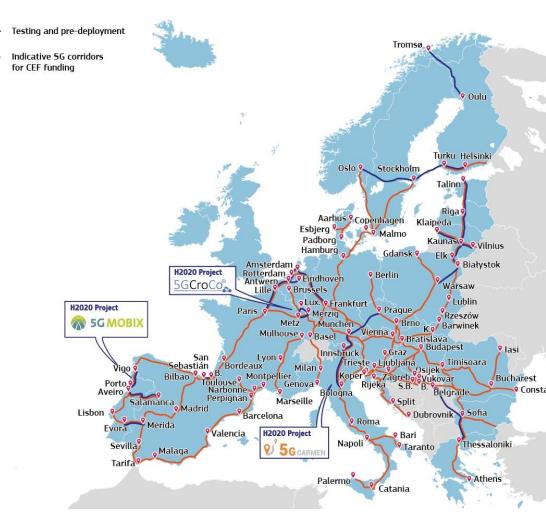


management

5G-MOBIX Background

- A 3-year project (11/2018-10/2021) funded within H2020 framework (ICT-18 call)
- 5G-MOBIX evaluates automotive use cases leveraging 5G technologies with a specific focus on cross-border areas
- Cross-border environment presents a number of challenging issues for 5G use cases with L4/L5 vehicles
 - Run cross-border experimental trials to test and validate potential solutions







5G-MOBIX – Two cross-border corridors (CBCs)



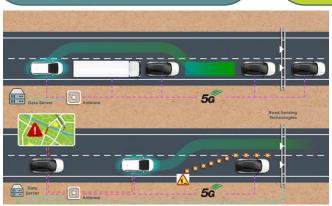
Spain - Portugal



Use cases

- Private Automated vehicles (SC1: Lane merge, SC2: Automated overtaking, SC3: HD MAPS)
- Public transport
- EV automated shuttle vehicles (SC1: Automated operation. SC2: Remote control.)

Porto – Vigo is a Pan-European X-Border 5G corridor for Connected and Automated Mobility







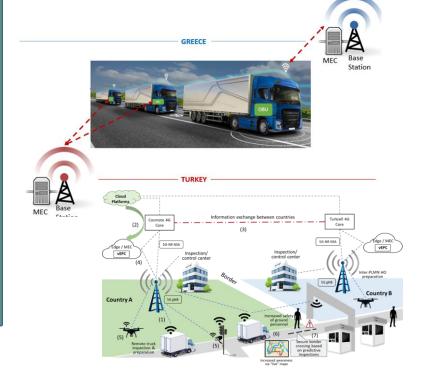
Greece - Turkey C*



Use cases

- Truck Platooning with "see what I see"
- Assisted Truck border crossing

Kipoi – Ipsala site is a main entry point into EU territory for cargo, with heavy customs operations





5G-MOBIX – Six Local Trial Sites (TS)

















55 partners from 10 countries

Telecom & Connectivity





















































































































5G-MOBIX use cases and addressed crossborder issues categorisation

5G-MOBIX Use Case Categorisation

Use case categorisation essential in 5G-MOBIX to enhance synergy between CBCs and TSs experimenting on common automotive use cases

5G-MOBIX Use Case Categories	Brief description	
Advanced driving	Vehicles (and/or RSU) in proximity share driving intentions and local sensor data obtained, thus allowing vehicles to coordinate their trajectories or maneuvers.	
Vehicles platooning	Enables the vehicles to dynamically form a group travelling together.	
Extended sensors	Exchange of raw or processed data gathered through local sensors or live video data among vehicles, RSUs, devices of pedestrians and V2X application servers.	
Remote driving	A human driver or a V2X application is able to remotely operate an autonomous vehicle.	
Vehicle QoS Support	A V2X application is timely notified of expected or estimated change of QoS before actual change occurs and/or mobile network able to modify the QoS in line with V2X application's QoS needs.	

3GPP TS 22.186 (2018-12). Enhancement of 3GPP support for V2X scenarios; Stage 1

QoS: Quality of Service RSU: Roadside Unit V2X: Vehicle to Everything



5G-MOBIX work on Cross-border issues

- Cross-border operation is the focus of 5G-MOBIX
- Addressed cross-border issues in four main categories
 - Telecommunication Issues
 - Application issues
 - Security and data privacy issues
 - Regulatory issues
- Distinct solutions to be applied and tested at the different cross-border corridors (CBCs) and local trial sites (TSs)



5G-MOBIX CBCs / TSs – Linking User Stories

- Focus on cross-border operation at the two CBC
 - Spain-Portugal (ES-PT)
 - Greece-Turkey (GR-TR)
- Local TS (e.g. FI) have been selected to contribute and enable the CBC trials (providing SW, components, alternatives, etc.)
- Extended evaluations requiring more controlled environments also performed at the TS

	Trial site	Advanced Driving	Vehicles Platooning	Extended Sensors	Remote Driving	Vehicle QoS Support
	ES-PT	Complex manoeuvres in cross-border settings		Extended sensors enabling complex manoeuvres	Automated shuttle remote driving across borders	Public transport with HD media services and video surveillance
	GR-TR		Platooning with "see what I see" functionality in cross-border settings	Extended sensors for assisted border crossing		
	DE		eRSU-assisted Platooning	EDM-enabled extended sensors with surround view generation		
í 	FI			Extended sensors with redundant Edge processing	Remote driving in a redundant network environment	
,	FR	Infrastructure- assisted advanced driving				QoS adaptation for security check in hybrid V2X environment
	NL	Cooperative Collision Avoidance		Extended sensors with CPM messages	Remote driving using 5G positioning	
	CN	Cloud-assisted Advanced Driving	Cloud-assisted platooning		Remote driving with data ownership focus	
	KR				Remote driving over mmW	Tethering via Vehicle over mmW





More details on FI trial site

Location & key stakeholders

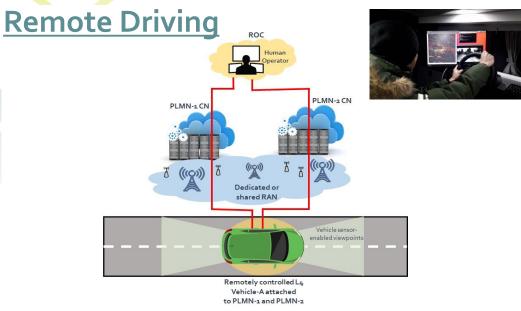
- Espoo Otaniemi
- Local 4G/5G test network
- 1.2 km of road (Otakaari & Maarintie)

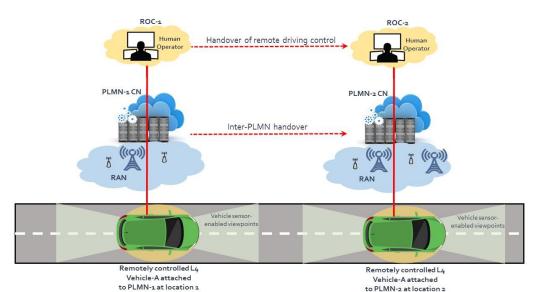
Key Role	Partner	Contribution		
SITE LEADER	A ?	Local test environment		
OEM	sensible ⁴	L ₄ vehicles		
Automotive vendor	VEDECOM	5G OBUs		

Other Stakeholders		Contribution		
MNO (1)	9 Telia	Operator perspectives		
Road authority (2)	TRAFICOM	Road and frequency regulator Perspectives from Nordic Way and Aurora corridors		

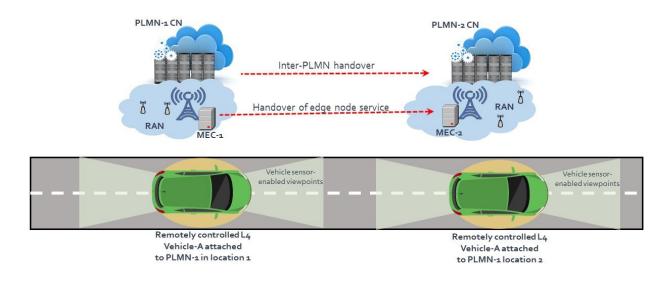


FI Trial Site User Stories (Use Cases)





Extended sensors

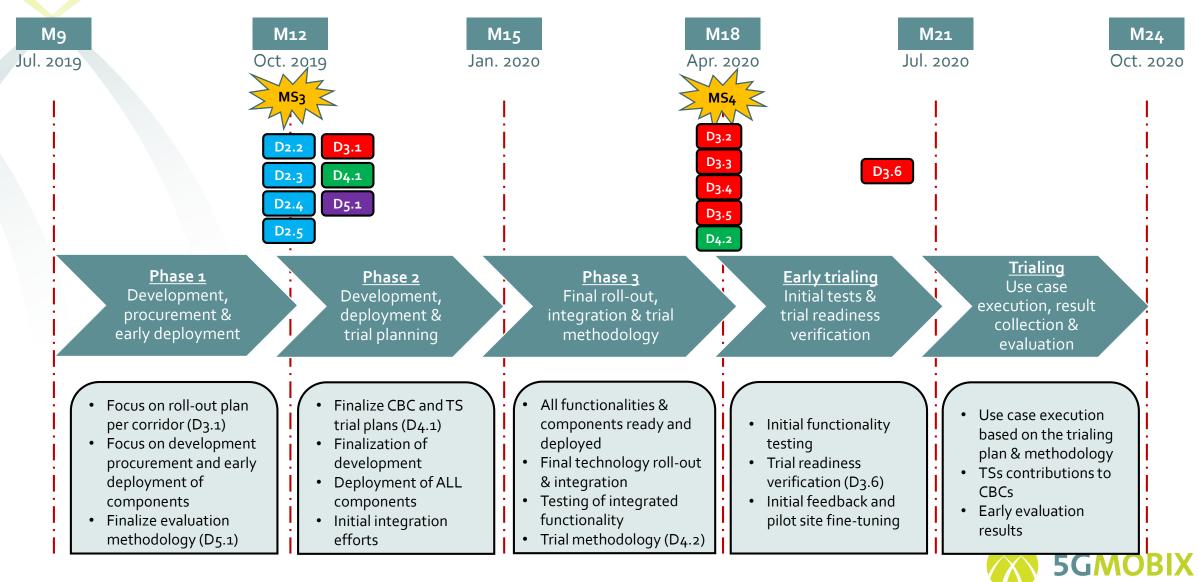


ROC: Remote Operations Centre



5G-MOBIX Technical Roadmap until M24

Trials from Q2 or Q3 2020 (also in FI site)



For Further Info

Welcome to our small stand at this event

- Or contact by email:
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 - Giancarlo Pastor Figueroa giancarlo.pastor@aalto.fi



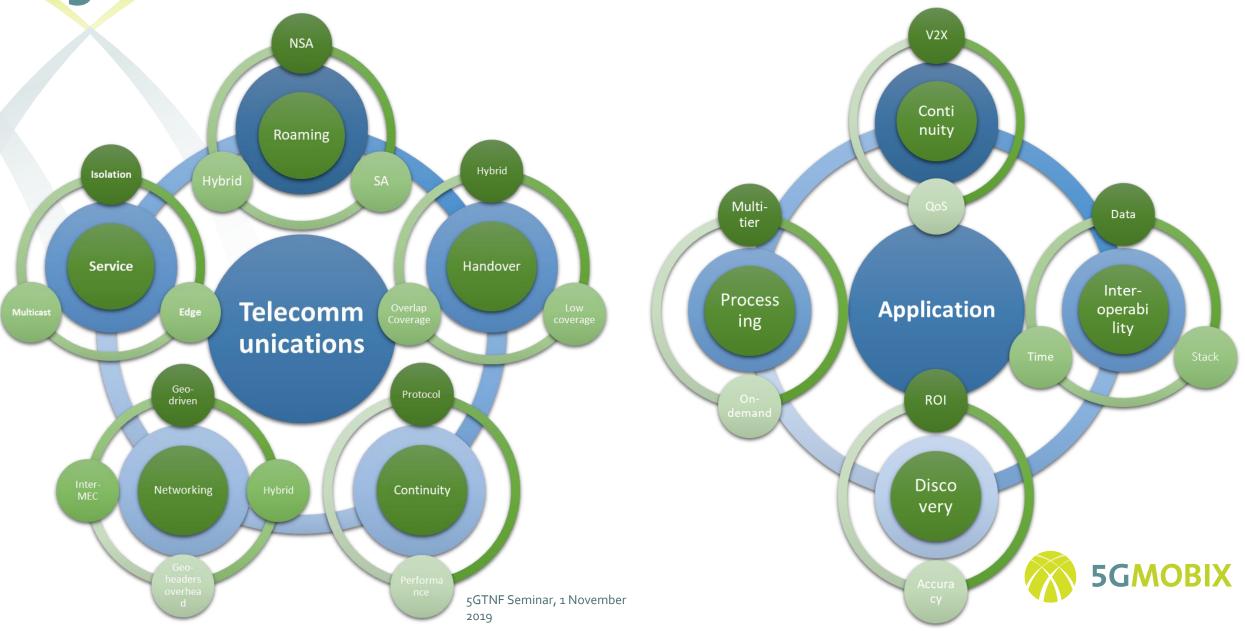
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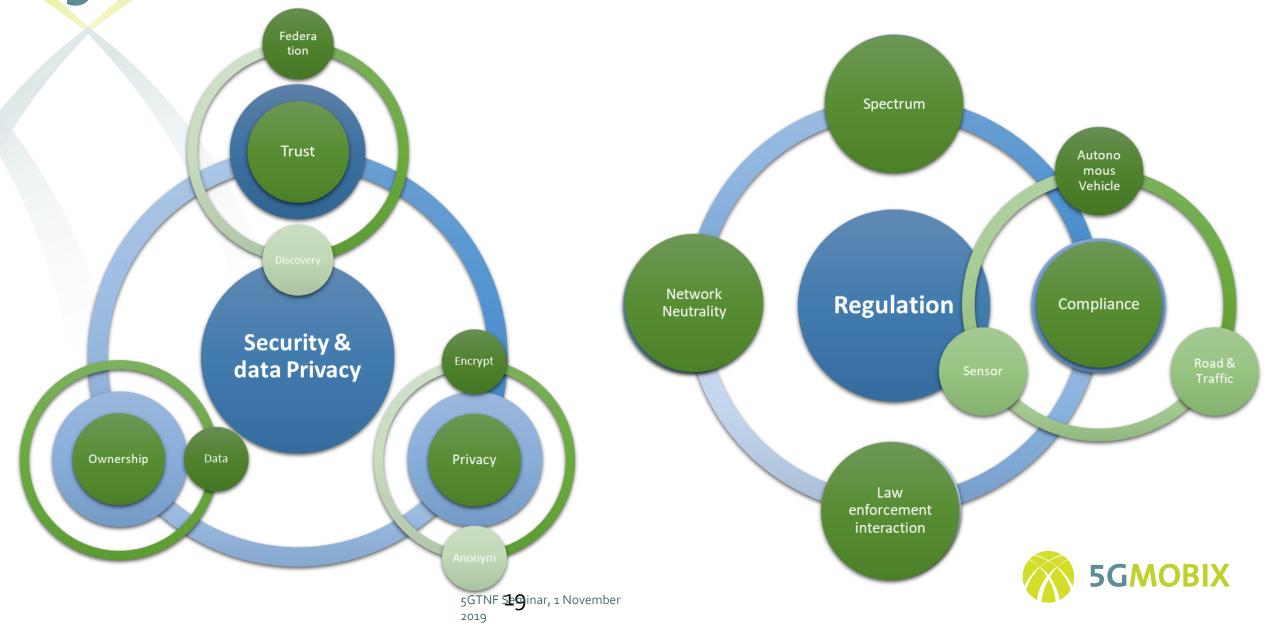
www.5g-mobix.com



5G-MOBIX Cross-border issues - Overview

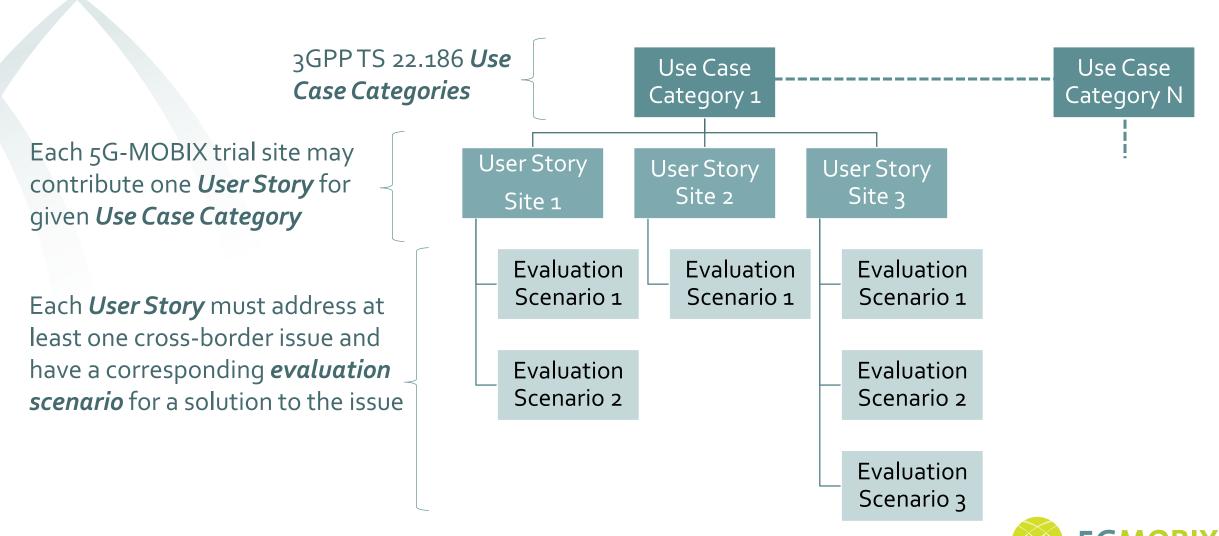


5G-MOBIX Cross-border issues – Overview



Hierarchy of 5G-MOBIX Trial Activities

5G-MOBIX experimental trial activities inspired by cross-border issues



5G-MOBIX Cross-border issues – Solutions under investigation

- Advanced Driving
 Use case Category
 (UCC#1)
- Multiple identified solutions
- Most promising progressed for evaluation through trialing
- TSs enable the evaluation of a much wider range of solutions
- Additional insights regarding configuration

Category	ID	Issue name	ES-PT	FR	NL	CN
Telecommunications	TR1	NSA Roaming Latency				
	TR ₂	SA Roaming Latency				
	TH1	Hybrid Handover Latency				
	TC1	Continuity Protocol				
	TC ₂	Performance Continuity				
	TN ₃	Geo Networking Overhead				
Application	AC1	V ₂ X Continuity				
	Alı	Data Interoperability				
	AP1	Real-time Multi-tier Processing				
Security & Data Privacy	ST1	Federation Trust				
	ST ₂	Discovery Trust				
	SP1	Data Privacy				
	SO ₁	Data Ownership				
Regulation	RC1	Autonomous Vehicle regulation Compliance				
	RC ₃	Sensor Compliance				
	RN1	Neutrality regulation				



5G-MOBIX CBCs / TSs – Illustrating Synergies

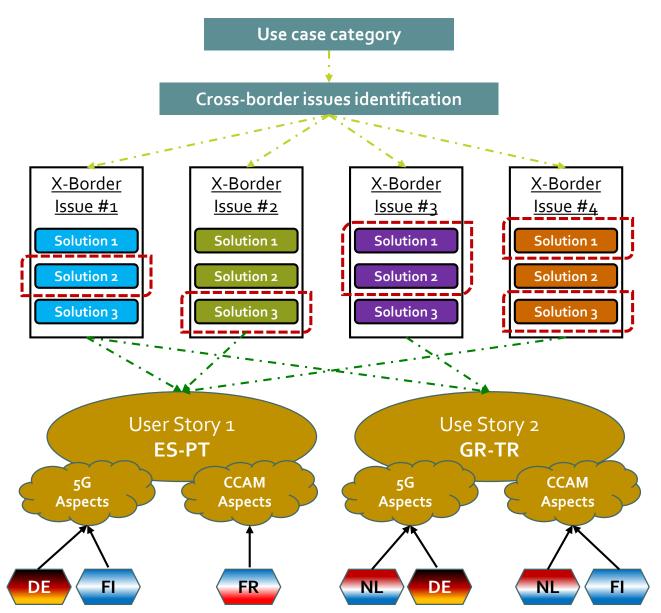
→ Identify the specific x-border issues of this use case category

→ For each cross-border issue identify the potential solutions

→ Test and evaluate the progressed solutions using specific user stories belonging to this use case category

→ Evaluation scenarios on 5G and CCAM aspects

→ Different TSs evaluate specific solutions to crossborder issues



CCAM: Cooperative, Connected and

Automated Mobility

ES-PT: Spain-Portugal corridor

DE: Germany trial site FI: Finland trial site

FR: France trial

GR-TR: Greece-Turkey corridor

NL: Netherland trial site X-border: Cross-border

