

### H2020 5G CCAM Project

With Participation of Nokia Bell Labs Spain

## Summary

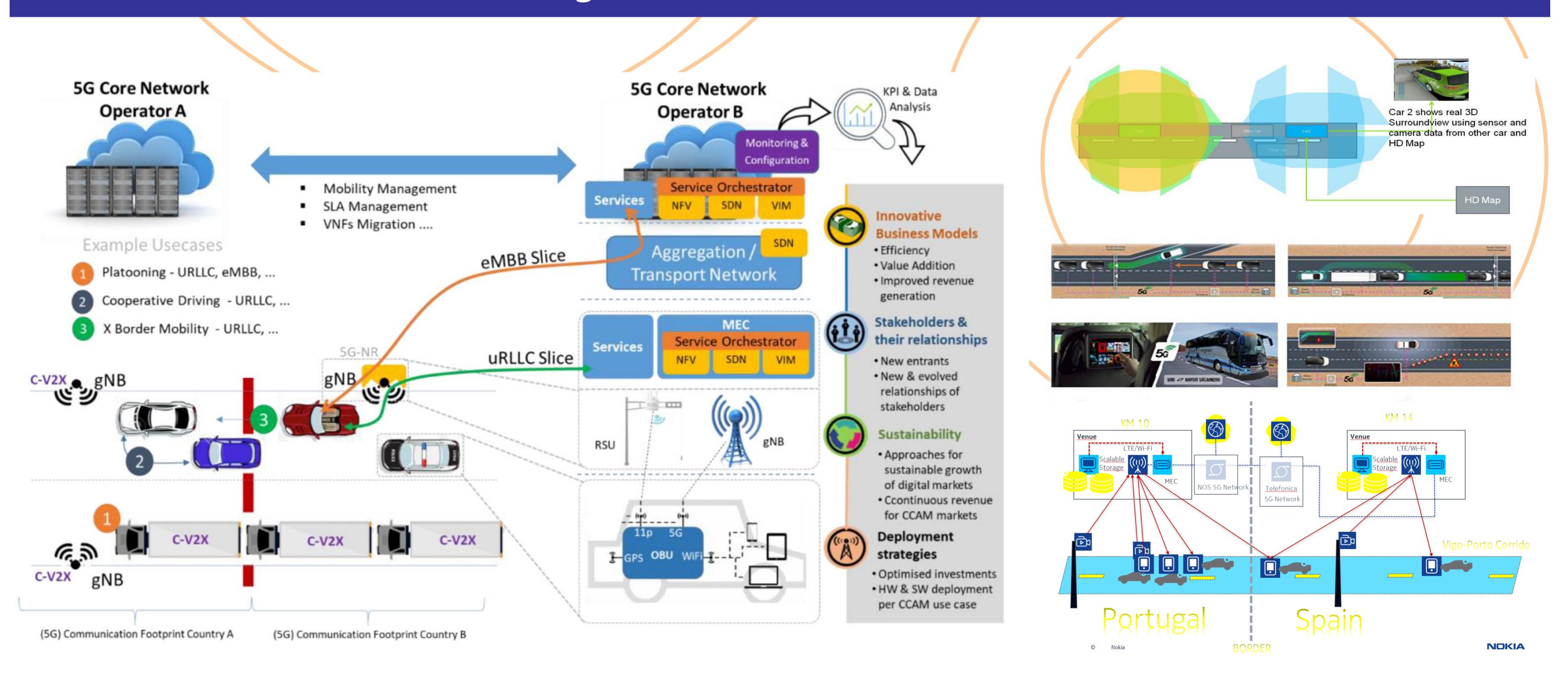
- ✓ 5G-MOBIX will develop and test automated vehicle functionalities along multiple cross-border corridors and urban trial sites, under all conditions of vehicular traffic, network coverage, service demand, considering the distinct legal, business and social local aspects.
- ✓ 5G-MOBIX aims at executing CCAM trials along x-border and urban corridors using 5G core technological

### Goals

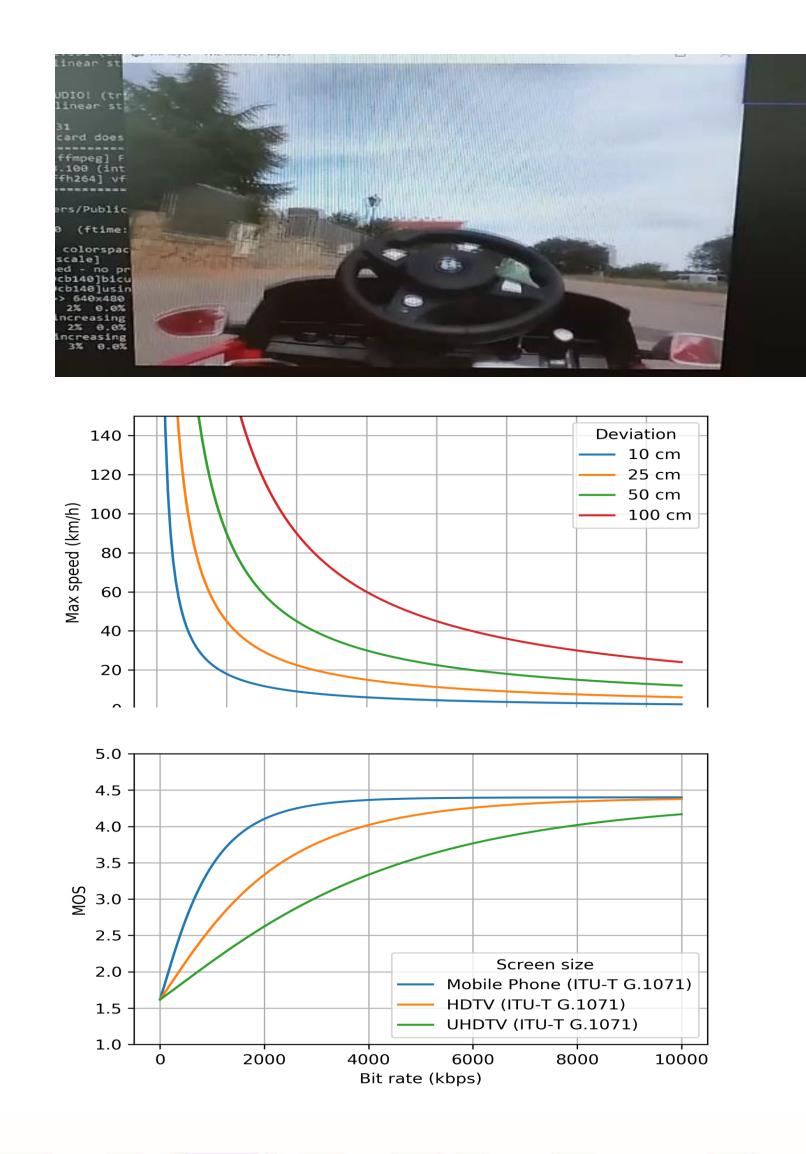
- Formulate a set of 5G technological requirements for advanced CCAM relevant for the automotive, telecom, IT, industries, and for R&D and public authorities.
- Establish corridors to evaluate 5G technologies and advanced CCAM in both highway cross-border and urban mobility scenarios.
- Analyze costs and benefits of dedicated and validate 5G architecture and CCAM to justify commercially the proposed recommendations.
- Explore and asses new business opportunities for CCAM with 5G.
- Provide 5G deployment scenarios and recommendations to drive CCAM adoption and effective implementations.
- Sustain standardization and spectrum allocation by actively contributing to the discourse.
- •Scale up and replicate for a global adoption of the 5G for CCAM.chitecture

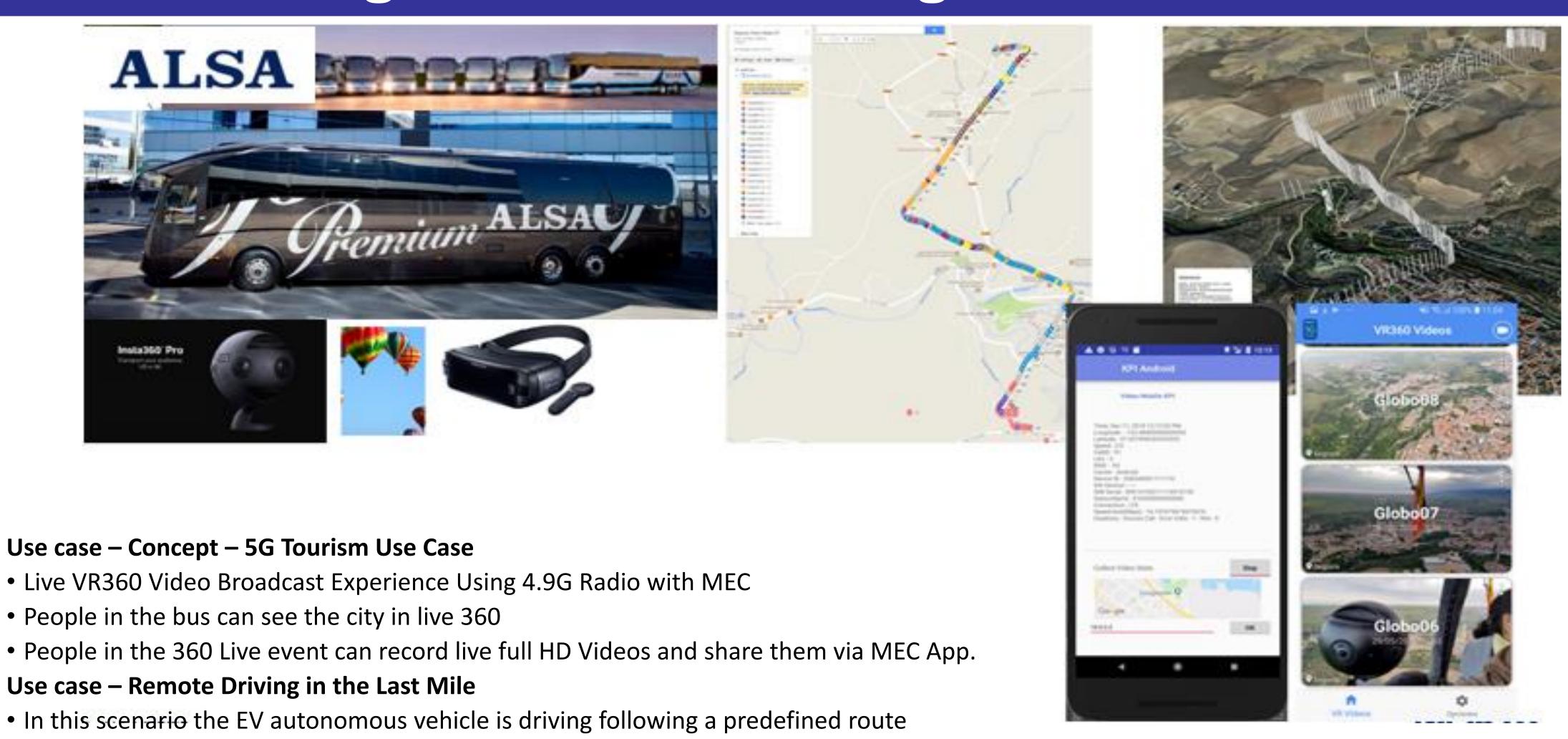
## Architecture and Remote Driving

### Connected Car – 5G Slicing and X-Border Deployments



# 5G Video Optimization Challenges Remote Driving and Infotainment









• If an obstacle appears in its path blocking the original route. In this situation, an operator is alarmed, and he/she



is able to remotely take the control of the EV autonomous vehicle in order to handle a new route.