Cross ICT-18-2018 White Paper

5G Trials for CCAM along European 5G Cross-Border Corridors

- Challenges and Opportunities

Part I

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5GPPP Webinar on 5G for CCAM, November 6th, 2020





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Introduction & Background

White Paper Background

- Three European IA projects (5G-CARMEN, 5G-CroCo & 5G-MOBIX) are currently investigating *5G-enabled CCAM in cross-border scenarios* under the EU-funded programme ICT-18-2018
- The three projects will realize *real-life trials in major European cross-border areas (corridors)* using 5G connectivity and state-of-the-art autonomous vehicles (up to SAE L₄)
- Trials are about to start, after a thorough requirements analysis, design, implementation and deployment process
- This WP presents the joint understanding of the three projects regarding the *key challenges* that need to be addressed in order to successfully *provision CCAM services at cross-border environments over 5G networks* and the most promising *technological enablers* that the projects are investigating

Problem statement: Why is it hard to provision CCAM over 5G at cross-border conditions?

- Currently all telecommunication/industrial/business procedures and operations have been designed to work on a *national level*, with no or minimal considerations for cross-border functionality
 - User mobility is almost exclusively treated with a network reselection (complete (long) interruption of communication and establishment of a new connection towards the visiting network), while CCAM applications require minimal to no interruption of service and very high throughput and extreme reliability!
 - Different communication laws and obligations apply in different countries
 - Network configuration is not/scarcely shared with foreign MNOs leading to *uncoordinated approaches*
- Original Equipment Manufacturers (OEMs) also face difficulties supporting CCAM functionalities across borders
 - No clear business model with significant additional costs (chipsets, antennas, validation costs, diagnosis/repair, calibration, etc.)
 - Potentially different national homologation rules and configuration requirements (e.g. supported frequency bands) for On Board equipment
 - Differentiated *regulations & liability* rules



White Paper Objectives

- Provide an overview of the goals and work being carried out within the three ICT-18 projects
- Provide an overview of the most prominent CCAM applications expected in cross-border environments and their respective requirements
- Analyse the key challenges that have to be addressed for CCAM support in cross-border environments, based on the work of the three projects
- Provide a list of candidate technological enablers and solutions that are/will be investigated within the projects and may potentially mitigate or resolve the identified challenges
- Increase visibility and engage the appropriate stakeholders as well as assist further research in the field (e.g. ICT-53 projects) by sharing currently available insights



Challenges Overview

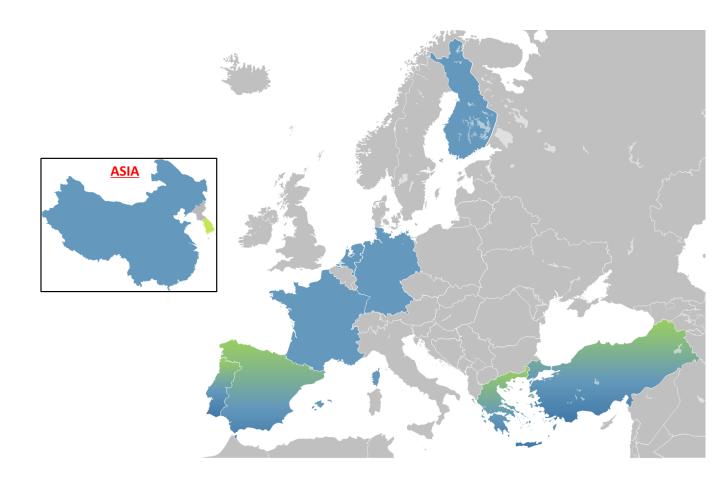
- Five high-level challenge categories have been defined, namely:
 - Cellular coverage and radio access aspects
 - Service and Session continuity aspects
 - MNO collaboration & Data Plane routing
 - Data management & protection
 - Non-functional aspects & business enablers
- The challenges cover technical, business, regulatory/legal and data management aspects
- Each Challenge ([Ch.#]) category is further broken down into specific issues/components and their impact and relevance is analysed
- A match between the identified challenges and the potential solutions that could mitigate their effect is presented at the end of the WP



5G-MOBIX overview

Overview of 5G-MOBIX CBCs / TSs

- 2 Cross-Border Corridors (CBC), i.e. ES-PT & GR-TR
- 4 complementary European Trial Sites (TS), i.e. DE, FI, FR, NL
- 2 complementary Asian Trial Sites (TS), i.e. CH, KR
- 5 Use case categories based on 3GPPTS 22.186, focusing on x-border operation
- 24 SAE L4 automated vehicles
- **30** 5G gNBs
- NSA Architecture + SA in national Trial Sites (FI, DE, NL)





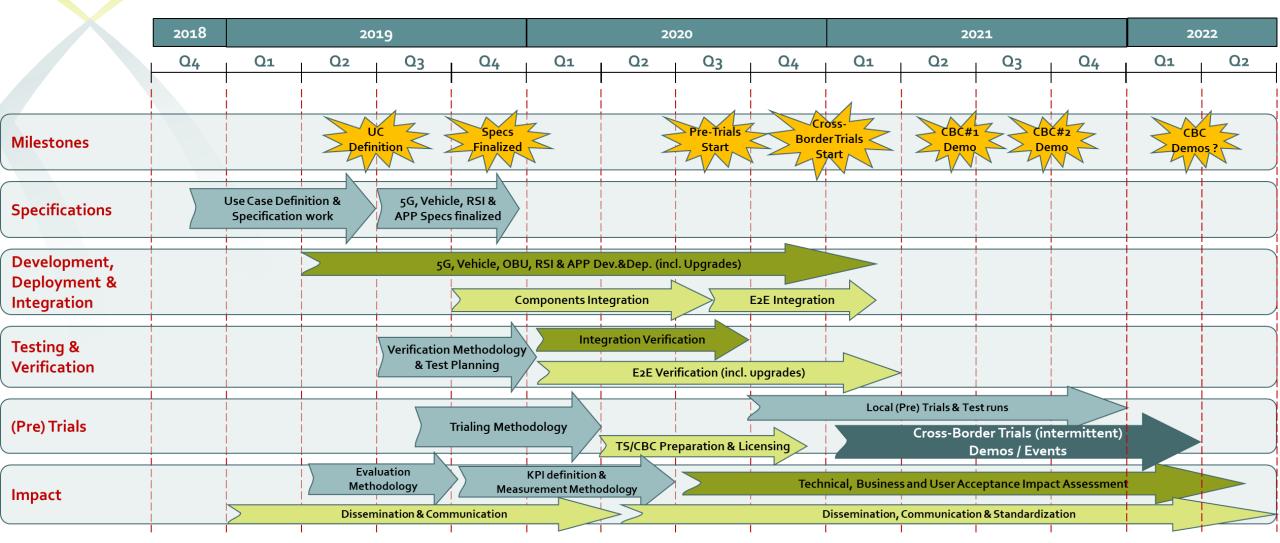
5G-MOBIX UCC/US overview & TS contributions

- Different architecture / technology may be used at different sites evaluating their performance
- Focus on cross-border operation at the two CBC
 - Spain-Portugal (ES-PT)
 - Greece-Turkey (GR-TR)
- Local TS have been selected to contribute and enable the CBC trials (providing SW, components, alternatives, etc.)
- Extended evaluations requiring controlled environments also performed at the TS

Trial site	Advanced Driving	Vehicles Platooning	Extended Sensors	Remote Driving	Vehicle QoS Support
→ ES-PT	Complex manoeuvres in cross-border settings			Automated shuttle remote driving across borders	Public transport with HD media services and video surveillance
GR-TR		Platooning with "see what I see" functionality in cross-border settings	Extended sensors for assisted border-crossing		
DE		eRSU-assisted platooning	EDM-enabled extended sensors with surround view generation		
FI			Extended sensors with redundant Edge processing	Remote driving in a redundant network environment	
FR FR	Infrastructure-assisted advanced driving				QoS adaptation for Security Check in hybrid V2X environment
NL	Cooperative Collision Avoidance		Extended sensors with CPM messages	Remote driving using 5G positioning	
CN	Cloud-assisted advanced driving	Cloud-assisted platooning		Remote driving with data ownership focus	
KR				Remote driving using mmWave communication	Tethering via Vehicle using mmWave communication



5G-MOBIX Roadmap



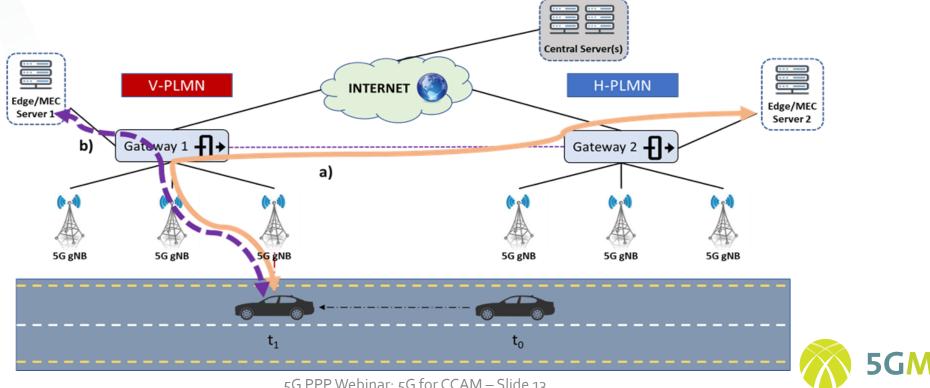


1st set of Challenges & potential solutions

(Service & Session Continuity, Data Plane Routing)

SSC Definitions & terminology

- **Session continuity**: The challenge of changing the attached gateway while maintaining the session (TS 23.501)
- Service continuity: The challenge of seamlessly switching the application server and host providing it





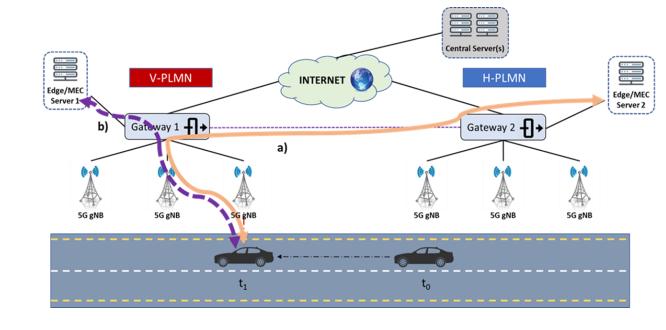
Service & Session Continuity

- Mobility events between neighbouring networks, require efficient gateway and edge/application server switches (under the mobility control plane)
- Session & Service Continuity (SSC) provides different levels of continuity for stateful applications → Very challenging for cross-border environments where both the network gateway and the edge/APP server need to be changed, while maintaining QoS/QoE based on SLA
 - How to handle the IP address change?
 - How to transfer the state of the UE/vehicle between edge nodes for stateful applications? Especially in the case where NAT is used?
 - How to maintain the agreed QoS/QoE during the transition without increasing the cost (e.g. double SIM solutions, SSC mode 3)?
 - What provisions need to be taken from the Application side (state transfer, communication of different instances across different networks)?



Data Plane routing

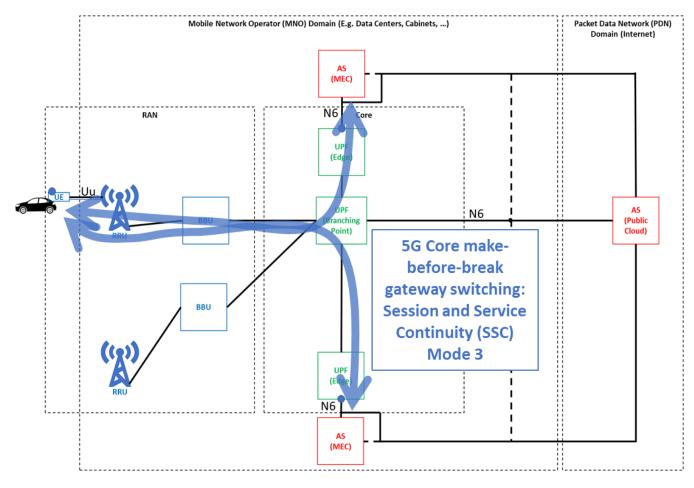
- Home Routing (HR) is the standard procedure, i.e. the anchor gateway remains at the Home network, even after the mobility event
 - HR allows for easier session continuity
 - Long routes created for the data transfer, which introduces additional delays
 - Not scalable through multiple networks
- Local Break-Out (LBO) may be used where the anchor gateway switches to the visiting network after the mobility event
 - Optimal smaller routes for data transfer
 - Switching of gateways introduces connectivity interruptions (SSC issue)
 - Need for exchange of UE data (roaming UEs, ongoing sessions) between the MNOs





Technological Enablers for SSC & Data Plane Routing

- Extensive use of Edge servers (MEC) benefits CAM applications with smaller data routes and reduced latencies. Variations of SSC approaches exist
- SSC mode 3 allows for a change of anchor gateway without temporary loss of connectivity but requires more advanced HW/UEs (promising but not available for testing)
- Cross-border / -MNO handover has already been standardized in 3GPP however not currently used by MNOs due to business, overhead/workload and legal/regulatory complexity





Technological Enablers for SSC & Data Plane Routing

- Standalone 5G New Radio with 5G Core allows to change the connection from Home- to Local Breakout Roaming without service interruption
- The Application Function (AF) may facilitate communication between the core and the application in order to *trigger the change of Edge/Application servers correctly* (on time)
- IP change of the vehicle & state transfer still needs to be addressed at the application level
 - Vehicle state may also be stored in-vehicle and communicated with new server instance
 - Context transfer between application servers (IP and DNS addressing may create complications)



Thank you



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